

ITMO UNIVERSITY

V-REP (LAB 3)

Teacher: Islam Bzhikhatlov.



Step 1

- Import assembly from SW(.stl)
- Set orientation (X or Y is vertical) and press OK.



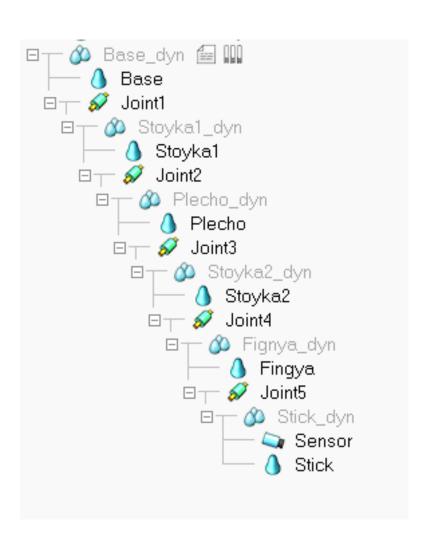
- Select all imported parts and generate "Convex Decomposition"
- Move all generated components to another layer.
- ▼ Turn off all layers except where layers with "Convex Decomposition".



- Add "Revolute joint"s to scene.
- Set correct positions for this joints
- Set correct orientations



- Assembly of mechanical structure
- Connect all parts in scene hierarchy
- All parts should be connected through the revolute joints.





- Set properties for "Convex Decomposition" base part as not "Dynamic".
- And tick as "respondable" also mask should be changed as shown on figure.

•	ndable mask ondable mask		
Material	defaultMaterial58 ▼ Edit		▼ Edit
		A	pply to selection
Body is dyna	mic		
Start in sle	ep mode	Set to dynamic if ge	ets parent
Compute m	ass & inertia pro	operties for selected cor	nvex shapes



- ✓ For all other "Convex Decomposition" set properties as Dynamic and respondable.
- Mask of all near parts should be different.

- Add "vision sensor" to latest part (tip of manipulator).
- Add "Graph"
- Add "data stream" and rename it like "Red_str"



STEP 8: Scripting

```
if (sim_call_type==sim_childscriptcall_initialization) then
    sensor=simGetObjectHandle('Sensor')
End

if (sim_call_type==sim_childscriptcall_actuation) then
    bu,data=simReadVisionSensor(sensor)
    simSetGraphUserData(graph,'Red_str',data[11])
End
```



Scene Object Properties	x
Graph	Common
Main properties	
Explicit handling	Object size [m] 0.100
✓ Buffer is cyclic	Buffer size 1000
✓ Display XYZ planes	Remove all static streams/curves
Time graph / xy graph properties	
✓ Display grids	Adjust background color
✓ Display grid values	Adjust graduation/grid color
Data stream recording list	
Add new data stream to reco	ord
Data transformations	
Value = Raw	+
Time graph properties	
Visible Show I	abel Link points
Adjust curve color	Duplicate curve to static
XY graphs / 3D curves	
Edit XY graphs	Edit 3D curves



Scene Object Properties		
Vision sensor	Common	
▼ Enable all vision sensors		
Main properties		
Explicit handling	External input	
Perspective mode	Ignore RGB info (faster)	
Use local lights	Ignore depth info (faster)	
✓ Show fog if enabled	Packet1 is blank (faster)	
Render mode OpenGL	*	
Near / far dipping plane [m]	5.00e-02 / 1.00e+00	
Persp. angle [deg] / ortho. size [m]	00.0100	
Resolution X / Y	4 / 4	
Entity to detect [Shape] Cuboic	. ▼	
Adjust default image color		
	Apply to selection	
isual properties		
Object size X - Y - Z [m] 0.010	- 0.010 - 0.030	
▼ Show volume when not detecting	Adjust color (passive)	
✓ Show volume when detecting	Adjust color (active)	
	Apply to selection	
mage processing and triggering		
Show filter	dialog	



Questions?

Some time for talking...



Thank you for attention!

bia@corp.ifmo.ru